



# International Driving TREC Rules

## PTV DATA SHEET

### 15 – UPWARD INCLINE

#### FEATURES

- Slope: 20° to 40 °
- Width: 3.50 meters minimum.

#### EQUIPMENT

- 2 red flags
- 2 white flags
- 1 number
- Marking for the obstacle route sand, plaster, etc.

#### OBJECTIVES

Moving through the obstacle at the highest initially chosen gait

#### EFFECTIVENESS FAULTS

- Break in forward motion, change of gait
- Running out
- Stepping back
- Refusal
- Circling

#### CHOICE OF GAIT

- Canter
- Trot
- Walk

***In the event of change in gait the slowest gait is taken, going back into the initial gait does not count in the score***

#### PENALITIES

- No whip in the hand
- Brutality
- Dangerous driving
- Foot or wheel out of the corridor
- Driver or groom stepping down from the carriage
- Carriage tipped
- Uncorrected course error



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## PTV SCORE SHEET

### 15 – UPWARD INCLINE

CORRIDOR N°																				
STEWARD:																				
Rider N°	E +	G -	P =	TOTAL	<p align="center"><b>MARKING SCHEME: E + G - P</b></p> <table border="1"> <thead> <tr> <th>Effectiveness E</th> <th>Gait G</th> <th>Penalty P</th> </tr> </thead> <tbody> <tr> <td>Correct 7</td> <td>canter +3</td> <td>No whip in the hand -10 Brutality -10</td> </tr> <tr> <td>1 fault 4</td> <td>trot 0</td> <td>Dangerous driving -10 Foot or wheel out of the corridor -10</td> </tr> <tr> <td>2 faults 1</td> <td>walk -2</td> <td>Foot on ground: driver or groom -30 Tipped carriage -50</td> </tr> <tr> <td>3 faults 0</td> <td></td> <td>Error of course eliminated</td> </tr> </tbody> </table> <p>A mark of 0 for effectiveness or as a penalty leads to an overall mark of 0</p>	Effectiveness E	Gait G	Penalty P	Correct 7	canter +3	No whip in the hand -10 Brutality -10	1 fault 4	trot 0	Dangerous driving -10 Foot or wheel out of the corridor -10	2 faults 1	walk -2	Foot on ground: driver or groom -30 Tipped carriage -50	3 faults 0		Error of course eliminated
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- 7 = no effectiveness fault: no break in forward motion, no running out, no refusal, no circling
- 4 = 1 effectiveness fault: 1 break in forward motion, etc.
- 1 = 2 effectiveness faults: 2 break in forward motion, etc.
- 0 = 3 effectiveness faults: etc ...